

# **Behavioral Game Theory: Predicting Human Behavior in a normal-form game**

# Agenda

Motivation (5 mins)

Related Fields (2 mins)

Models (10 mins)

Quantal Response Equilibrium

Bounded Iterative Reasoning (Level-K & Cognitive Hierarchy)

Discussion (3 mins)

# Agenda

Motivation

Related Fields

Models

Discussion

# Traveler's Dilemma

## Motivational Example

“We know that the bags have identical contents, and we will entertain any claim between \$180 and \$300, but you will each be reimbursed at an amount that equals the *minimum* of the two claims submitted. If the two claims differ, we will also pay a reward  $R$  to the person making the smaller claim and we will deduct a penalty  $R$  from the reimbursement to the person making the larger claim.”

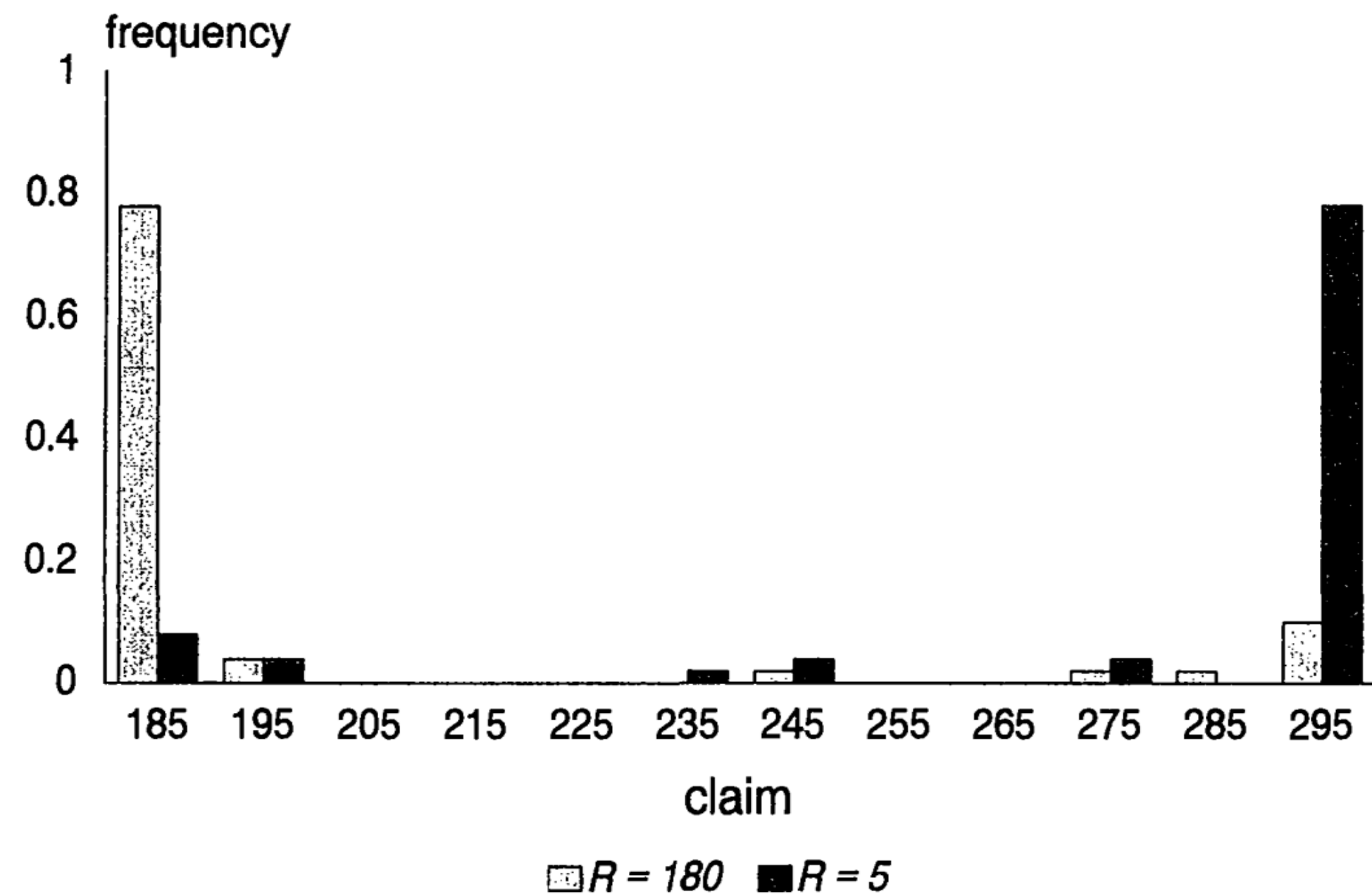
- **Experimental results deviate from NE**
  - $R=5$ , 11/12 (91.7%) of the class did not play Nash.
  - We are so irrational! (except Sophie)

# Experimental results deviates from NE

[Goeree, Holt, 2001]

[\$180, \$300],  $R=5$ ,  $R=180$

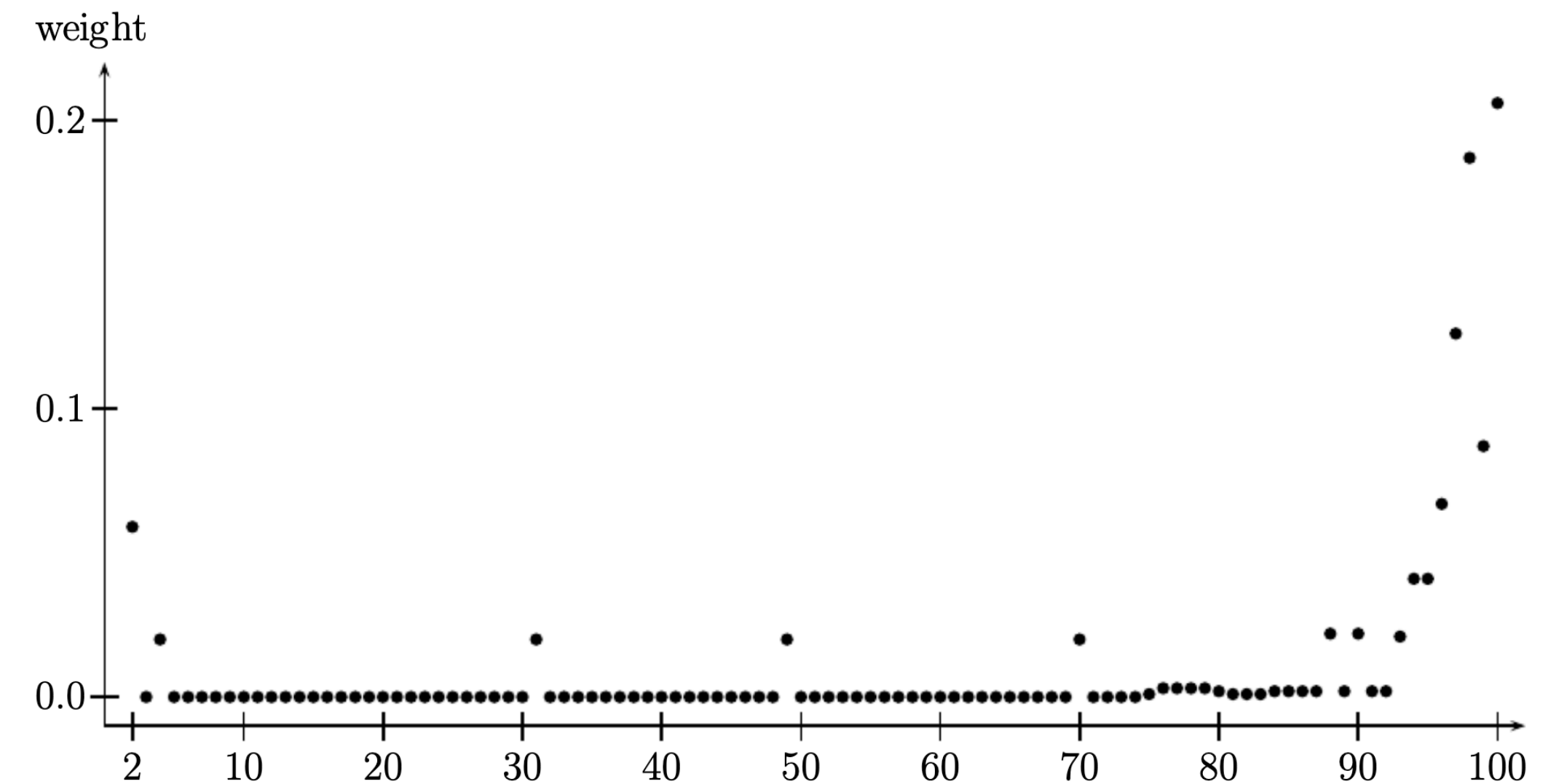
50 random subjects (25 pairs)  
~80% claimed the highest amount  
\$300, average claim \$280



[Becker, et al. 2005]

[\$2, \$100],  $R=2$

51 members of Game Theory Society  
~20% played highest amount



**Behavioral Game Theory (BGT)  
seeks to explain this deviation.**

# Agenda

Motivation

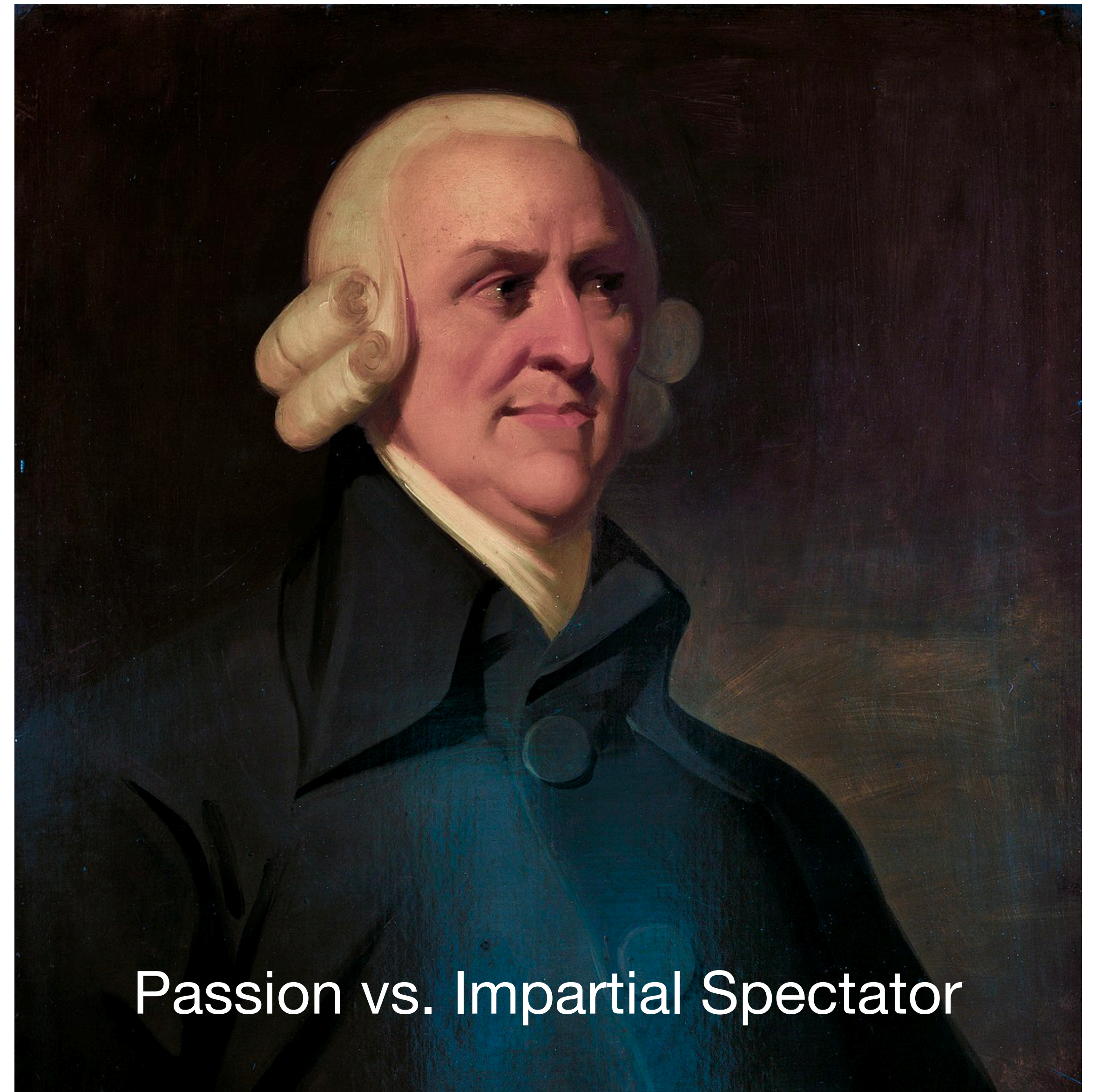
**Related Fields**

Models

Discussion

# Behavioural Economics

- concerned with bounded rationality of economic agents
- studies market decisions, public opinions
- Examples:
  - Loss aversion
  - Fairness
  - Discounted Utility



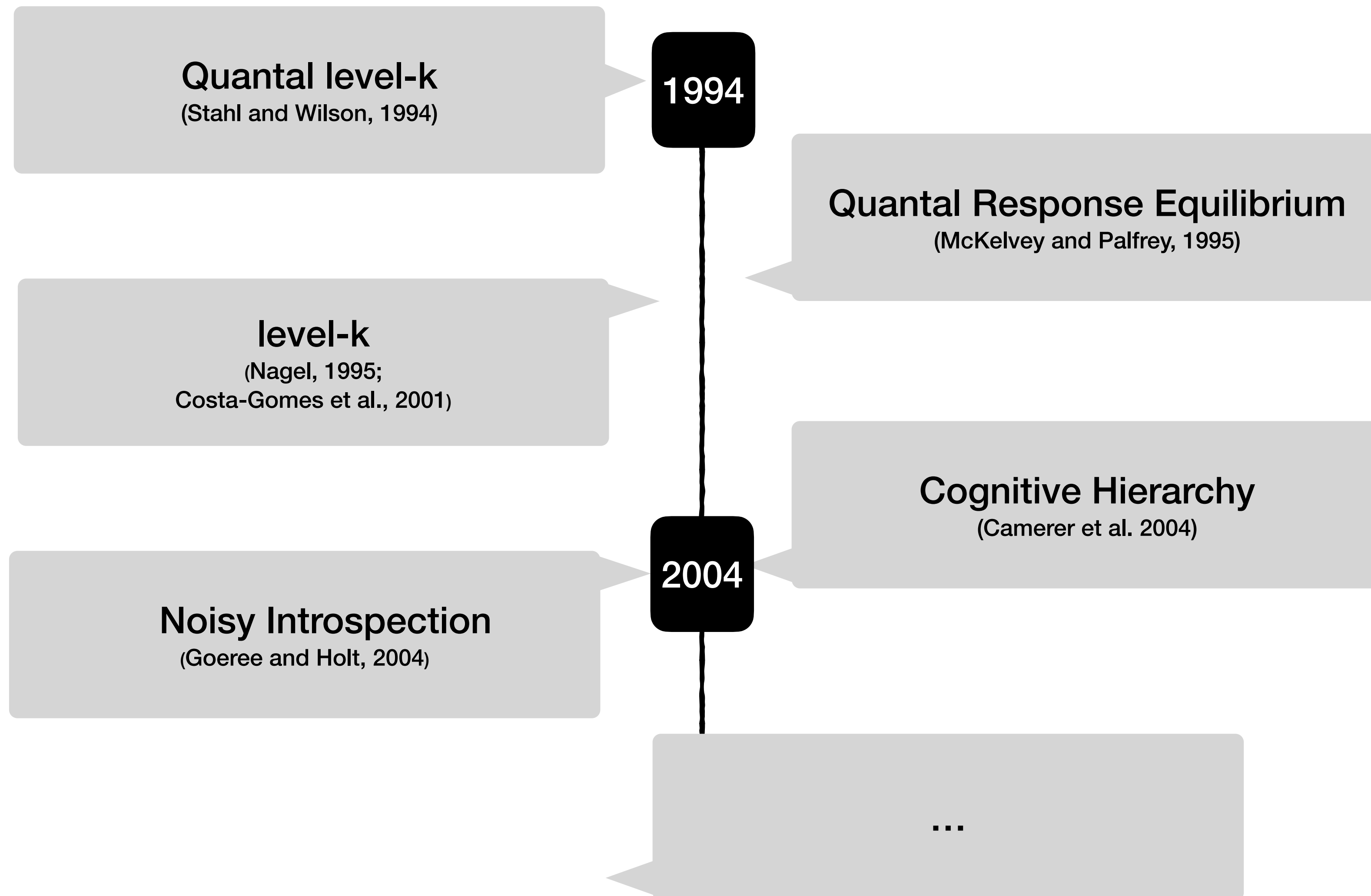
Passion vs. Impartial Spectator



# Psychology

- Methods
  - Experimental psychology
- Concepts
  - Emotions (fear, regret, shame etc.)
  - Deeper motivations (reciprocity, guilt)
- Complex and dynamic, hard to quantize into utility

# BGT in unrepeated normal-form games



# Agenda

Motivation

Related Fields

**Models:**

**Behavioral Model:**

$$P(a_i | G_i, \theta)$$

Quantal Response Equilibrium

Bounded Iterative Reasoning (Level-K & Cognitive Hierarchy)

Discussion

# Agenda

Motivation

Related Fields

**Models:**

**Quantal Response Equilibrium**

Bounded Iterative Reasoning (Level-K & Cognitive Hierarchy)

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# Quantal Response Equilibrium (QRE)

McKelvey and Palfrey, 1995

- Intuition:
  - Players can make errors, but less likely when error gets more costly.
- Key idea: maximizing expected utility with some noise

$$\hat{u}_i(a_i, s_{-i}) = \underbrace{u_i(a_i, s_{-i})}_{\text{true utility}} + \underbrace{\epsilon_{a_i}}_{\text{noise}}$$

# Quantal Response Equilibrium (QRE)

Given  $\hat{u}_i(a_i, s_{-i}) = \underbrace{u_i(a_i, s_{-i})}_{\text{true utility}} + \underbrace{\epsilon_{a_i}}_{\text{noise}}$

QRE is a strategy profile  $s^*$  where for every agent  $i$  :

$$\hat{u}_i(s^*) \in \arg \max_{s_i} \hat{u}(s_i, s_{-i}^*)$$

Similar to NE, a **quantal response equilibrium** is a mixed strategy profile in which every agent's strategy is a **quantal best response** to the strategies of the other agents.

# Logit Quantal Best Response

“precision”: How sensitive agents are to utility differences

$$s_i^*(a_i) = \frac{e^{\lambda \cdot u_i(a_i, s_{-i}^*)}}{\sum_{a'_i} e^{\lambda \cdot u_i(a'_i, s_{-i}^*)}}$$

$\lambda = 0$ , Uniform Distribution

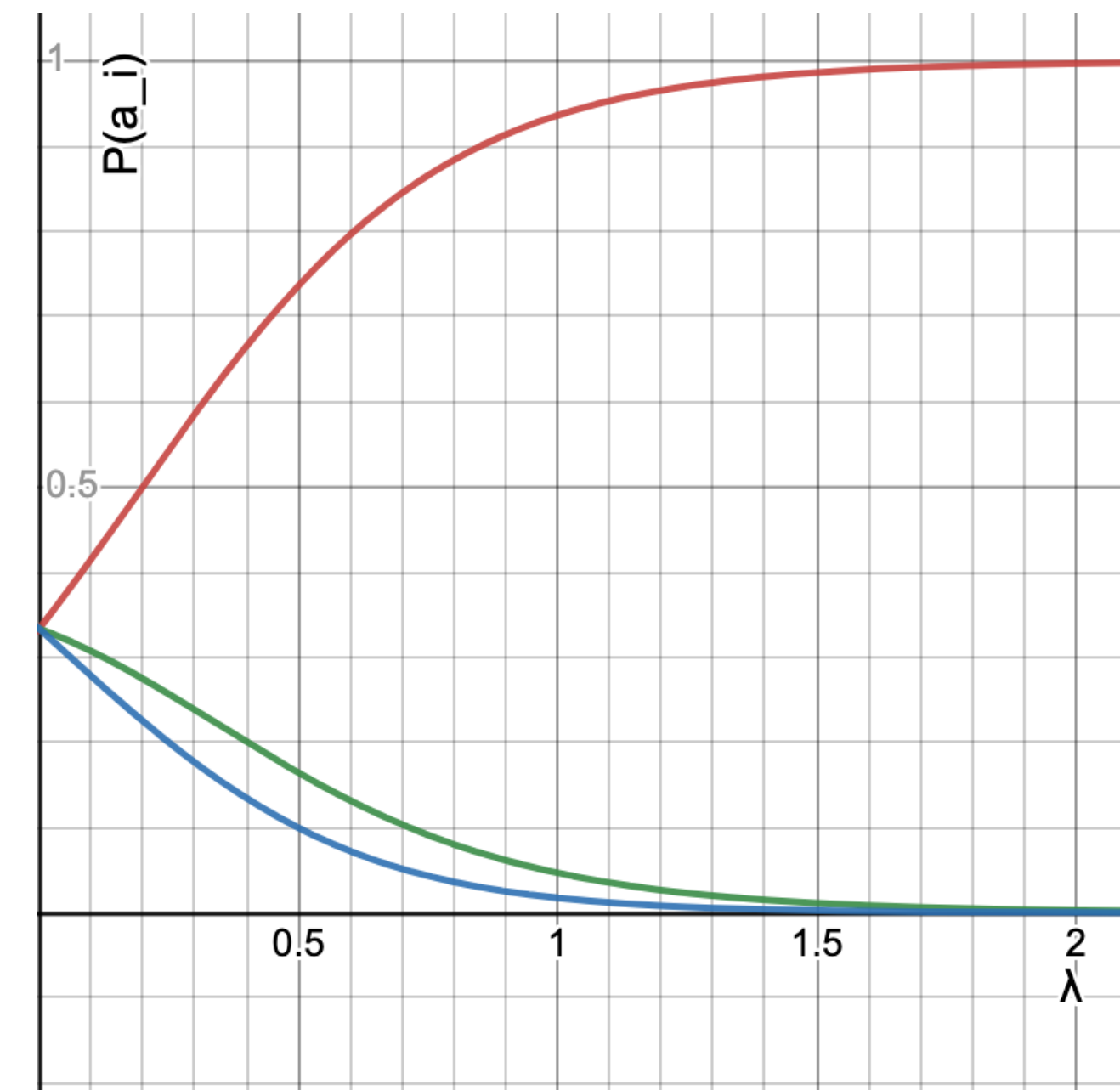
$\lambda \rightarrow +\infty$ , Nash Equilibrium

Example:

One player,

3 action choices with utility [6, 3, 2]

visualization of its action probabilities:



# Revisit Traveler's Dilemma with QRE

- Experiments show dramatic shifting of claims with change of penalty.
- **Well tracked** by QRE.
- Noise can “snowball”.

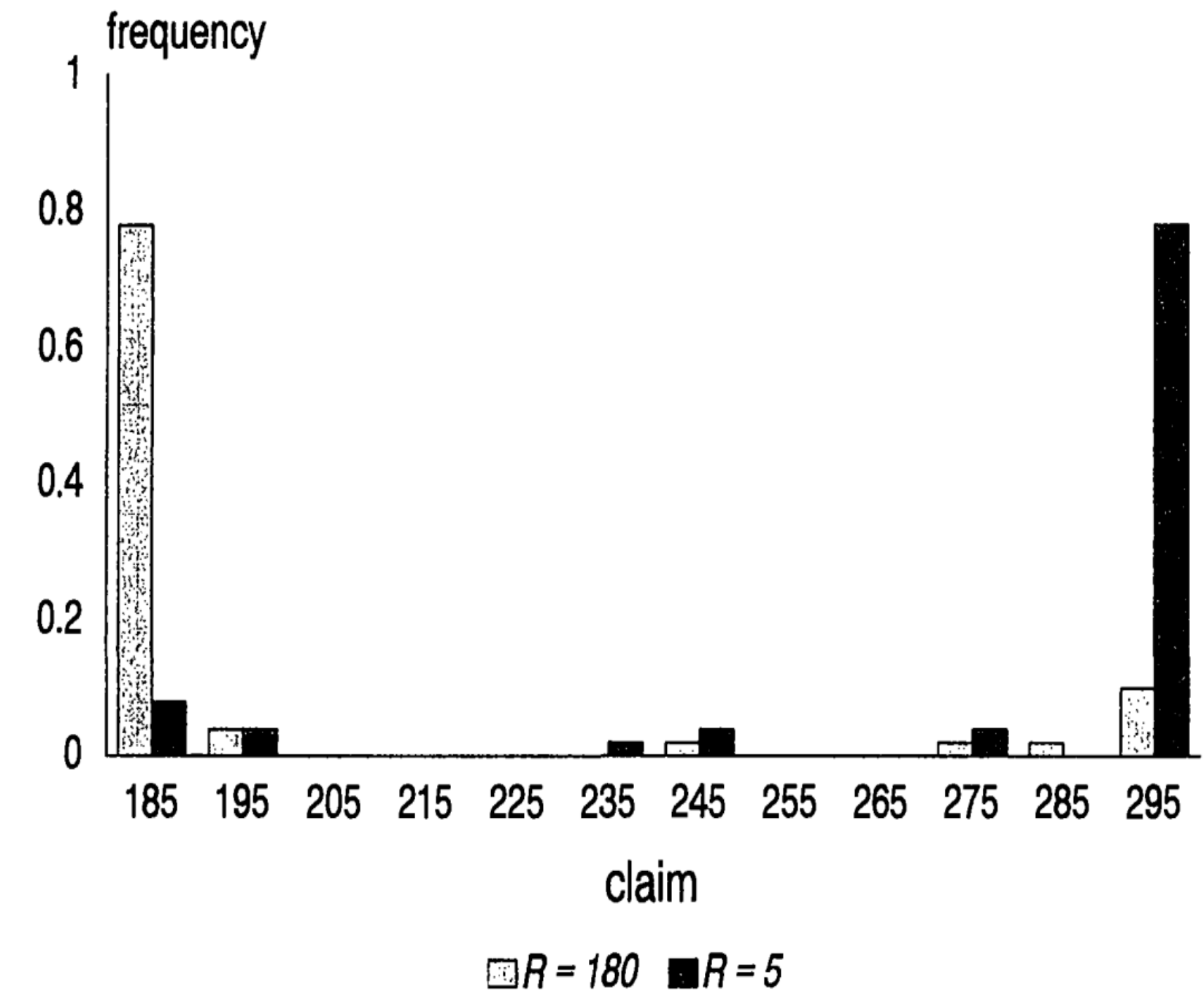


FIGURE 1. CLAIM FREQUENCIES IN A TRAVELER'S DILEMMA FOR  $R = 180$  (LIGHT BARS) AND  $R = 5$  (DARK BARS)



# Agenda

Motivation

Related Fields

**Models:**

Quantal Response Equilibrium

**Bounded Iterative Reasoning (Level-K & Cognitive Hierarchy)**

Discussion

# Level-k Thinking

(Stahl and Wilson, 1995; Nagel, 1995)

- Each player assumes their strategy is the most **sophisticated** (degree of recursion)
- Inductively defined strategies:
  - step 0 players: randomize
  - step 1 players: best respond to step 0 players
  - ...
  - step k players: best respond to step k-1 players

# Cognitive Hierarchy

(Camerer et al. 2004)

- Each player assumes their strategy is the most sophisticated
- Inductively defined strategies:
  - step 0 players: randomize
  - step 1 players: best respond to step 0 players
  - ...
  - step k players: best respond to players **distributed over step 0 to k-1**

# Revisit Traveler's Dilemma

## With Bounded Iterative Reasoning

- Most of us played \$300, but some played differently
  - \$180
  - \$298?
  - \$295?

# Agenda

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# Discussion and Limitations

- The two paradigms often make similar and improved predictions for experimental results.
- Many models similar to their variants or a mixture of both.
- Subject to overfitting.
- Cognitive Hierarchy and Level-K assumed uniform strategies of level-0 agents; this does not seem plausible.

# Summary

- Behavioural Game Theory is concerned with what **human** do in a game. They explain **experimental results** sometimes better than NE.
- **Quantal Response** introduces noises in action probabilities around best responses, **QRE** is the equilibrium where such responses are considered.
- **Cognitive Hierarchy and Level-K Thinking** assumed bounded depth of iterative reasoning, when players try to reason about what the other players think.
- Although the above models focus on explaining observations, recent development in BGT seeks to predict and generalize.

# Paradox of Rationality

**“Players who make irrational or naïve choices often receive better payoffs and that those making the rational choices predicted by backward induction often receive worse outcomes.”**



# References

## Primary sources (plus the ones on slides)

Ten Little Treasures of Game Theory and Ten Intuitive Contradictions, Goeree and Holt, 2001

Beyond Equilibrium: Predicting Human Behaviour in Normal Form Games, J.R. Wright 2010

Modeling Human Behavior in Strategic Settings, J.R. Wright, 2016

Predicting human behavior in unrepeated, simultaneous-move games, Wright and Leyton-Brown, 2017

A Cognitive Hierarchy Model of Games, Camerer, 2004

A Case for Behavioural Game Theory, Sarah Bonau, 2017

# Noise distribution assumption for LQRE

In the rest of the paper, we study a particular parametric class of quantal response functions that has a tradition in the study of individual choice behavior (Luce, 1959). For any given  $\lambda \geq 0$ , the *logistic* quantal response function is defined, for  $x_i \in \mathbb{R}^{J_i}$ , by

$$\sigma_{ij}(x_i) = \frac{e^{\lambda x_{ij}}}{\sum_{k=1}^{J_i} e^{\lambda x_{ik}}}$$

with player  $i$ , action  $j \in J_i$

$$\hat{u}_{ij} = u_{ij} + \underline{\varepsilon}_{ij}$$

$\varepsilon_i = (\varepsilon_{i1}, \dots, \varepsilon_{iJ_i}) \sim$  distribution with PDF  $f_i(\varepsilon_i)$

and corresponds to optimal choice behavior<sup>4</sup> if  $f_i$  has an extreme value distribution, with cumulative density function  $F_i(\varepsilon_{ij}) = e^{-e^{-\lambda \varepsilon_{ij} - \gamma}}$  and the  $\varepsilon_{ij}$ 's are independent. Therefore, if each player uses a logistic quantal response function, the corresponding QRE or *Logit Equilibrium* requires, for each  $i, j$ ,

$$\pi_{ij} = \frac{e^{\lambda x_{ij}}}{\sum_{k=1}^{J_i} e^{\lambda x_{ik}}}$$

where  $x_{ij} = \bar{u}_{ij}(\pi)$ .

(marginal distribution of  $f_i$  exists for each  $\varepsilon_{ij}$  and  $E(\varepsilon_i) = 0$ )